

Chapter Four

Solving Systems of Non-linear Equations

In this chapter, we consider the problem of finding roots of simultaneous nonlinear equations. For simplicity we shall consider only the case of two equations in two unknowns.

$$\left. \begin{array}{l} f(x, y) = 0 \\ g(x, y) = 0 \end{array} \right\} \dots\dots\dots(1)$$

We shall study three numerical methods to solve this type of systems:

(i) Fixed-point iteration (for systems):

As a first step in applying fixed-point iteration, we rewrite these equations in the equivalent form

$$\left. \begin{array}{l} x = F(x, y) \\ y = G(x, y) \end{array} \right\} \dots\dots\dots(2)$$

So that any solution of (2) is a solution of (1), and conversely. Let $\{\lambda, \mu\}$ be a solution of

(1), i.e. $\left. \begin{array}{l} f(\lambda, \mu) = 0 \\ g(\lambda, \mu) = 0 \end{array} \right\}$. Let $\{x_0, y_0\}$ be an approximation to $\{\lambda, \mu\}$. Generate successive

approximations from the recursion

$$\left. \begin{array}{l} x_{i+1} = F(x_i, y_i) \\ y_{i+1} = G(x_i, y_i) \end{array} \right\}, i=0, 1, 2, \dots \dots\dots(3)$$

Stop iteration if $|x_{i+1}-x_i|<\epsilon$ and $|y_{i+1}-y_i|<\epsilon$ for any i .

It is shown in analysis this iteration will converge under the following (but not necessary) conditions:

- a. F and G and their partial derivatives are continuous in a neighborhood \mathfrak{R} of the roots $\{\lambda, \mu\}$, where \mathfrak{R} consists of all $\{x, y\}$ with $|x-\lambda| \leq \epsilon$, $|y-\mu| \leq \epsilon$, for some positive ϵ .

- b. The following inequalities are satisfied $\left. \begin{array}{l} |F_x| + |G_x| \leq K \\ |F_y| + |G_y| \leq K \end{array} \right\}$ for all points $\{x, y\}$ in \mathfrak{R} and some $K < 1$.

- c. The initial approximations $\{x_0, y_0\}$ is chosen in \mathfrak{R} .

Note:

When this iteration does converge it converges linearly.

To proof (b):

$$\begin{aligned} x_1 &= F(x_0, y_0) & \lambda &= F(\lambda, \mu) \\ y_1 &= G(x_0, y_0) & \mu &= G(\lambda, \mu) \end{aligned} \cdot$$

$$x_1 - \lambda = F(x_0, y_0) - F(\lambda, \mu)$$

$$y_1 - \mu = G(x_0, y_0) - G(\lambda, \mu)$$

By using Taylor series expansion about λ and μ we get

$$F(x_0, y_0) = F(\lambda, \mu) + (x_0 - \lambda)(F_x)_{(x_0, y_0)} + (y_0 - \mu)(F_y)_{(x_0, y_0)} + \dots$$

$$G(x_0, y_0) = G(\lambda, \mu) + (x_0 - \lambda)(G_x)_{(x_0, y_0)} + (y_0 - \mu)(G_y)_{(x_0, y_0)} + \dots$$

$$\text{Let } K = \max \left\{ |F_x|_{(x_0, y_0)} + |G_x|_{(x_0, y_0)}, |F_y|_{(x_0, y_0)} + |G_y|_{(x_0, y_0)} \right\}$$

$$\begin{aligned} \therefore |x_1 - \lambda| + |y_1 - \mu| &\leq |x_0 - \lambda| \left\{ |F_x|_{(x_0, y_0)} + |G_x|_{(x_0, y_0)} \right\} + |y_0 - \mu| \left\{ |F_y|_{(x_0, y_0)} + |G_y|_{(x_0, y_0)} \right\} \\ &\leq K \left\{ |x_0 - \lambda| + |y_0 - \mu| \right\} \end{aligned}$$

Similarly,

$$|x_2 - \lambda| + |y_2 - \mu| \leq K \left\{ |x_1 - \lambda| + |y_1 - \mu| \right\} \leq K^2 \left\{ |x_0 - \lambda| + |y_0 - \mu| \right\}$$

⋮

$$|x_n - \lambda| + |y_n - \mu| \leq K^n \left\{ |x_0 - \lambda| + |y_0 - \mu| \right\}$$

The value of $|x_0 - \lambda|$ and $|y_0 - \mu|$ must approach to zero and this happens, when $K < 1$ $\{K^n \rightarrow 0 \text{ as } n \rightarrow \infty\}$. Hence the condition $K < 1$ is sufficient to force the convergence.

Example 1:

Solve the following system:

$$0.1x^2 + 0.1y^2 - x + 0.8 = 0$$

$$0.1x + 0.1xy^2 - y + 0.8 = 0 \text{ where } x_0 = y_0 = \frac{1}{5}.$$

The exact solution of this system is $x = y = 1$.

Solution:

Rewrite above system as follows:

$$x = 0.1x^2 + 0.1y^2 + 0.8 = F(x, y)$$

$$y = 0.1x + 0.1xy^2 + 0.8 = G(x, y)$$

We see that $\left|F_x\right|_{(0.5, 0.5)} + \left|G_x\right|_{(0.5, 0.5)} = 0.144 < 1$, hence the iteration converge. Applying $\left|F_y\right|_{(0.5, 0.5)} + \left|G_y\right|_{(0.5, 0.5)} = 0.48 < 1$

iteration form (3) we obtain the successive approximations in this table

i	x _i	y _i
0	0.5	0.5
1	0.85	0.8625
2	0.94664	0.94823
3	0.97953	0.97978
4	0.99182	0.99196

(ii) Newton-Raphson method:

To adapt Newton-Raphson method to simultaneous equations, we proceed as follows: Let {x₀,y₀} be an approximation to the solution {λ,μ} of (1). Assuming that f and g are sufficiently differentiable, expand f(x,y), g(x,y) about {x₀,y₀} using Taylor series for functions of two variables:

$$f(x,y)=f(x_0,y_0)+f_x(x_0,y_0)(x-x_0)+f_y(x_0,y_0)(y-y_0)+\dots$$

$$g(x,y)=g(x_0,y_0)+g_x(x_0,y_0)(x-x_0)+g_y(x_0,y_0)(y-y_0)+\dots$$

Assuming that {x₀,y₀} sufficiently closed to {λ,μ} so that higher order terms can be neglected, we equate the expansion through linear terms to zero. This gives us the system

$$\left. \begin{aligned} f_x(x-x_0)+f_y(y-y_0) &\approx -f \\ g_x(x-x_0)+g_y(y-y_0) &\approx -g \end{aligned} \right\} \dots\dots\dots(*)$$

where it is understood that all functions and derivatives in (*) are to be evaluated at {x₀,y₀}. We might then expect that the solution {x₁,y₁} of (*) will be closer to the solution {λ,μ} than {x₀,y₀}. The solution of (*) by Cramer's rule yields

$$\left| x_1 - x_0 \right| = \frac{\begin{vmatrix} -f & f_y \\ -g & g_y \end{vmatrix}}{\begin{vmatrix} f_x & f_y \\ g_x & g_y \end{vmatrix}} = \left[\frac{-fg_y + df_y}{J(f, g)} \right]_{\{x_0, y_0\}} ; \quad \left| y_1 - y_0 \right| = \frac{\begin{vmatrix} f_x & -f \\ g_x & -g \end{vmatrix}}{\begin{vmatrix} f_x & f_y \\ g_x & g_y \end{vmatrix}} = \left[\frac{-gf_x + fg_x}{J(f, g)} \right]_{\{x_0, y_0\}}$$

Provided that J(f,g)=f_xg_y-g_xf_y≠0 at {x₀,y₀}. The function J(f,g) is called the Jacobian of the functions f and g. The solution {x₁,y₁} of this system now provides a

new approximation to $\{\lambda, \mu\}$. Repetition of this process leads to Newton-Raphson method for systems

$$x_{i+1} = x_i - \left[\frac{fg_y - gf_y}{J(f, g)} \right]_{(x_i, y_i)} ; \quad y_{i+1} = y_i - \left[\frac{gf_x - fg_x}{J(f, g)} \right]_{(x_i, y_i)} ; i=0, 1, \dots$$

Where $J(f, g) = f_x g_y - g_x f_y$ and where all functions involved are to be evaluated at $\{x_i, y_i\}$.

Stop iteration if $|x_{i+1} - x_i| < \varepsilon$ and $|y_{i+1} - y_i| < \varepsilon$ for any i .

When this iteration converges, it converges quadratically.

A set of conditions sufficient to ensure convergence is the following:

1. f, g and all their derivatives through second order are continuous and bounded in a region \mathfrak{R} containing $\{\lambda, \mu\}$.
2. The Jacobian $J(f, g)$ dose not vanish in \mathfrak{R} .
3. The initial approximation $\{x_0, y_0\}$ is chosen sufficiently close to the root $\{\lambda, \mu\}$.

Example 2:

Solve the system

$$x^2 + y^2 = 1$$

$$x^2 - y^2 = -0.5 \text{ at } \{x_0, y_0\} = \{0.1, 0.3\} \text{ also at } \{x_0, y_0\} = \{0.5, 0.5\}.$$

Solution:

$$\text{Let } f(x, y) = x^2 + y^2 - 1 = 0$$

$$g(x, y) = x^2 - y^2 + 0.5 = 0$$

$$\therefore f_x = 2x, f_y = 2y, g_x = 2x, g_y = -2y$$

$$\text{at } \{x_0, y_0\} = \{0.1, 0.3\} \Rightarrow f(0.1, 0.3) = -0.9, \quad f_x = 0.2, f_y = 0.6, g(0.1, 0.3) = 0.42, \quad g_x = 0.2, \\ g_y = -0.6$$

$$x_1 = x_0 - \left[\frac{fg_y - gf_y}{J(f, g)} \right]_{(x_0, y_0)} = 0.1 - \left[\frac{(-0.9 \times -0.6) - (0.42 \times 0.6)}{(0.2 \times -0.6) - (0.6 \times 0.2)} \right] = 0.1 - \frac{0.288}{-0.24} = 1.3$$

$$\therefore y_1 = y_0 - \left[\frac{gf_x - fg_x}{J(f, g)} \right]_{(x_0, y_0)} = 0.3 - \left[\frac{(0.42 \times 0.2) - (-0.9 \times 0.2)}{(0.2 \times -0.6) - (0.6 \times 0.2)} \right] = 0.3 - \frac{0.264}{-0.24} = 1.4$$

Also

$$x_2 = x_1 - \left[\frac{fg_y - gf_y}{J(f, g)} \right]_{(x_1, y_1)} = 1.3 - \left[\frac{fg_y - gf_y}{J(f, g)} \right]_{(1.3, 1.4)} = ?$$

$$y_2 = y_1 - \left[\frac{gf_x - fg_x}{J(f, g)} \right]_{(x_1, y_1)} = 1.4 - \left[\frac{gf_x - fg_x}{J(f, g)} \right]_{(1.3, 1.4)} = ?$$

⋮

(iii) Modified Newton-Raphson method:

Newton-Raphson method is not very easy in general for n simultaneous equations in n unknowns. But in Modified Newton-Raphson method we sue the idea of Newton-Raphson method for single variable as follows:

For nonlinear system $\begin{cases} f(x, y) = 0 \\ g(x, y) = 0 \end{cases}$

$$x_{i+1} = x_i - \left[\frac{f}{f_x} \right]_{\{x_i, y_i\}} ; \quad y_{i+1} = y_i - \left[\frac{g}{g_y} \right]_{\{x_{i+1}, y_i\}} ; i=0, 1, \dots$$

Stop iteration if $|x_{i+1}-x_i|<\varepsilon$ and $|y_{i+1}-y_i|<\varepsilon$ for any i.

Also for nonlinear system $\begin{cases} f(x, y, z) = 0 \\ g(x, y, z) = 0 \\ h(x, y, z) = 0 \end{cases}$

$$x_{i+1} = x_i - \left[\frac{f}{f_x} \right]_{\{x_i, y_i, z_i\}} ; \quad y_{i+1} = y_i - \left[\frac{g}{g_y} \right]_{\{x_{i+1}, y_i, z_i\}} ; \quad z_{i+1} = z_i - \left[\frac{h}{h_z} \right]_{\{x_{i+1}, y_{i+1}, z_i\}} ;$$

For i=0, 1, ...

Stop iteration if $|x_{i+1}-x_i|<\varepsilon$, $|y_{i+1}-y_i|<\varepsilon$ and $|z_{i+1}-z_i|<\varepsilon$ for any i.