



# **Color Edge Detection Using Jacobian-Vector Value Method**

***Prepared by:***

***Dr. Sarah Behnam Aziz***

*College of Sciences,*

*Computer Science &IT Department*

*Salahaddin University*

*Erbil, IRAQ-KRG*

*sarah.aziz@su.edu.krd*

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# Agenda

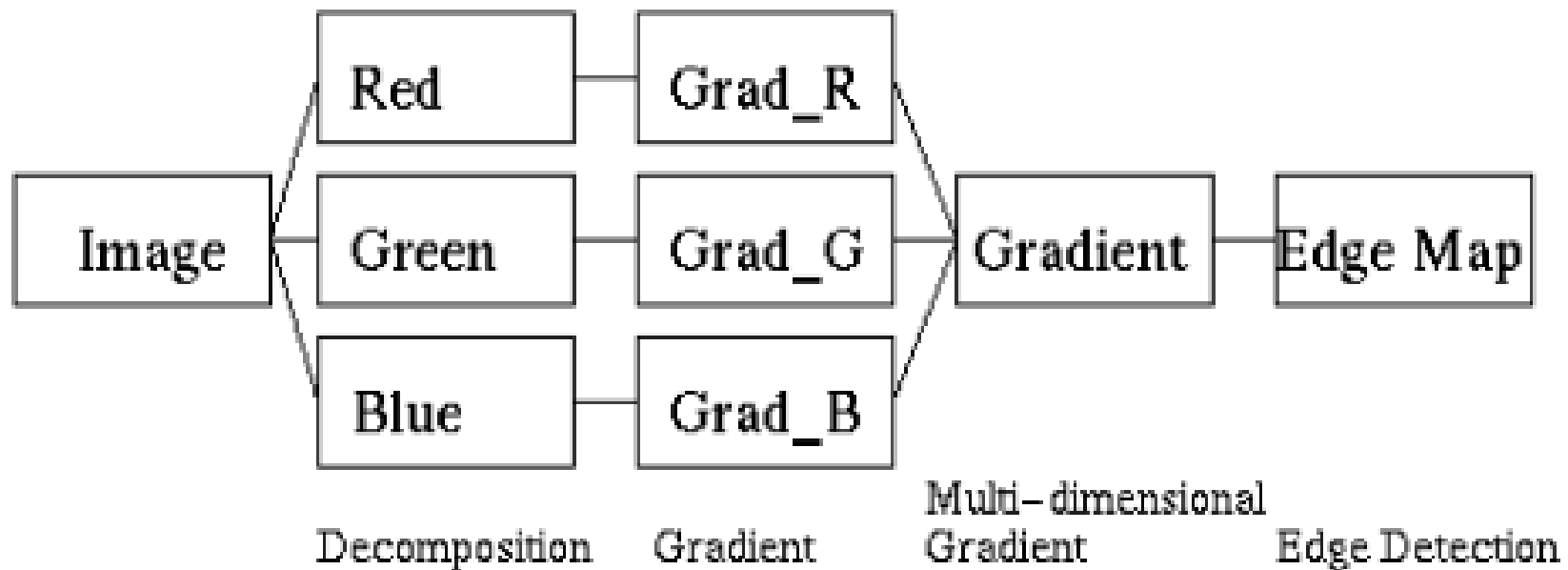
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# Introduction

- Edge detection plays an important role in image processing, pattern recognition and computer vision applications.
- The edge can be defined as a boundary between an object and the background.
- Most of edge detection schemes are based on finding maximum in the first derivative of the image function such as Roberts operator, Sobel operator, Prewitt operator.
- The others seek in the second derivative zero-crossing to edge detection, such as LOG operator, Canny operator.
- Various methods of edge detection for color images, including techniques extended from monochrome edge detection as well as vector space methods are presented.

# Vector Value Method

- The vector-valued technique is applied on the color images and isolate individual component of RGB.



- The direct formulas for the Jacobian eigenvalues were used, so this function is vectorized and yields good results without sacrificing performance.

# Steps of Jacobian-Vector value Method

- Determine the standard edge detection operator that will to be applied.
- Compute the x-direction derivative ( $r_x$ ,  $g_x$ , and  $b_x$ ) for the three color component (RGB) separately.
- Compute the y-direction derivative ( $r_y$ ,  $g_y$ , and  $b_y$ ) for the three color component (RGB) separately.
- Compute the Jacobian matrix for the x-direction derivatives, y-direction derivatives and their combination.

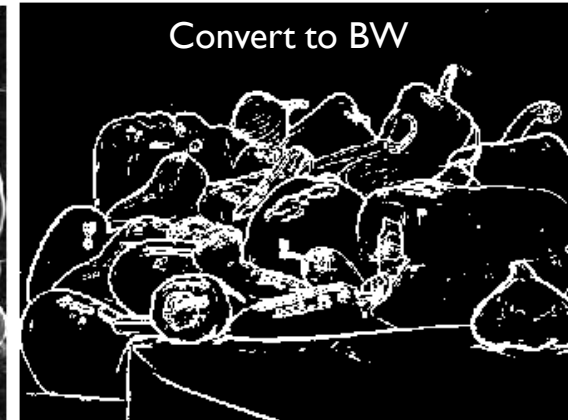
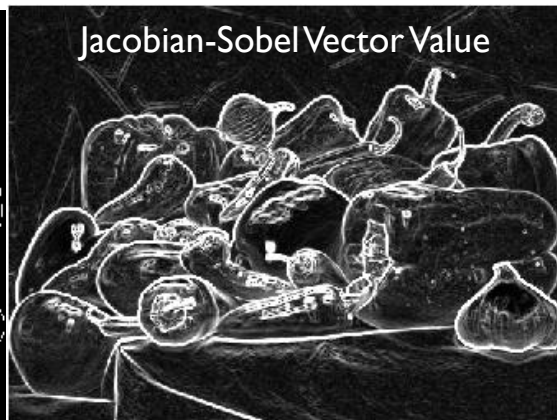
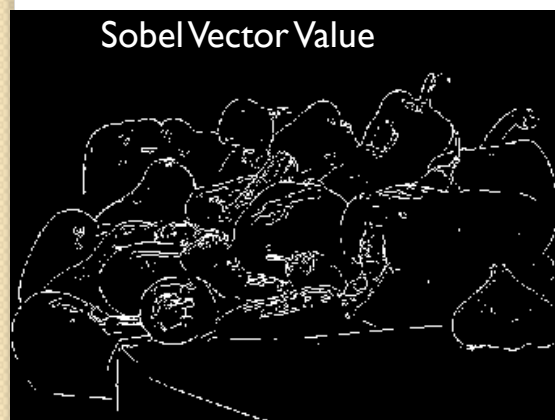
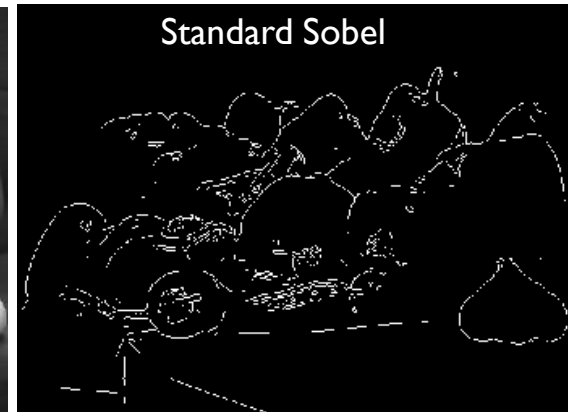
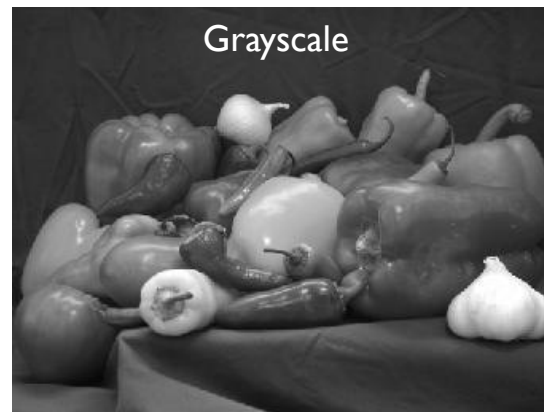
$$J_x = r_x^2 + g_x^2 + b_x^2$$

$$J_y = r_y^2 + g_y^2 + b_y^2$$

$$J_{xy} = r_x * r_y + g_x * g_y + b_x * b_y$$

- compute first (greatest) eigenvalue ( $e_1$ ) of  $2 \times 2$  matrix  $J' * J$ .  
 $D = \sqrt{\text{abs}(J_x^2 - 2 * J_x * J_y + J_y^2 + 4 * J_{xy}^2)}$   
 $e_1 = (J_x + J_y + D) / 2$
- Find the edge magnitude.  
edge magnitude =  $\sqrt{e_1}$

# Results



# Conclusion

- Extracts the edges of a color image without converting it to grayscale.
- Changes in color are detected even when the grayscale color of two pixels are the same.
- The edge strength is typically greater or equal to the magnitude obtained by simply filtering a grayscale image.
- Optionally, the edge orientation can also be returned.

$$\text{edge\_orientation} = \tan^{-1}(-J_{xy}, |J_x - J_y|);$$

# References

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Thank You!

